

<b>DTC</b>	<b>C0371/71</b>	<b>Yaw Rate Sensor (Test Mode DTC)</b>
<b>DTC</b>	<b>C1232/32</b>	<b>Stuck in Deceleration Sensor</b>
<b>DTC</b>	<b>C1234/34</b>	<b>Yaw Rate Sensor Malfunction</b>
<b>DTC</b>	<b>C1243/43</b>	<b>Deceleration Sensor Stuck Malfunction</b>
<b>DTC</b>	<b>C1244/44</b>	<b>Open or Short in Deceleration Sensor Circuit</b>
<b>DTC</b>	<b>C1245/45</b>	<b>Deceleration Sensor Output Malfunction</b>
<b>DTC</b>	<b>C1279/79</b>	<b>Deceleration Sensor Output Voltage Malfunction (Test Mode DTC)</b>
<b>DTC</b>	<b>C1381/97</b>	<b>Yaw Rate and / or Acceleration Sensor Power Supply Voltage Malfunction</b>

## DESCRIPTION

The skid control ECU receives signals from the yaw rate sensor and deceleration sensor via the CAN communication system.

The deceleration sensor is built into the yaw rate sensor.

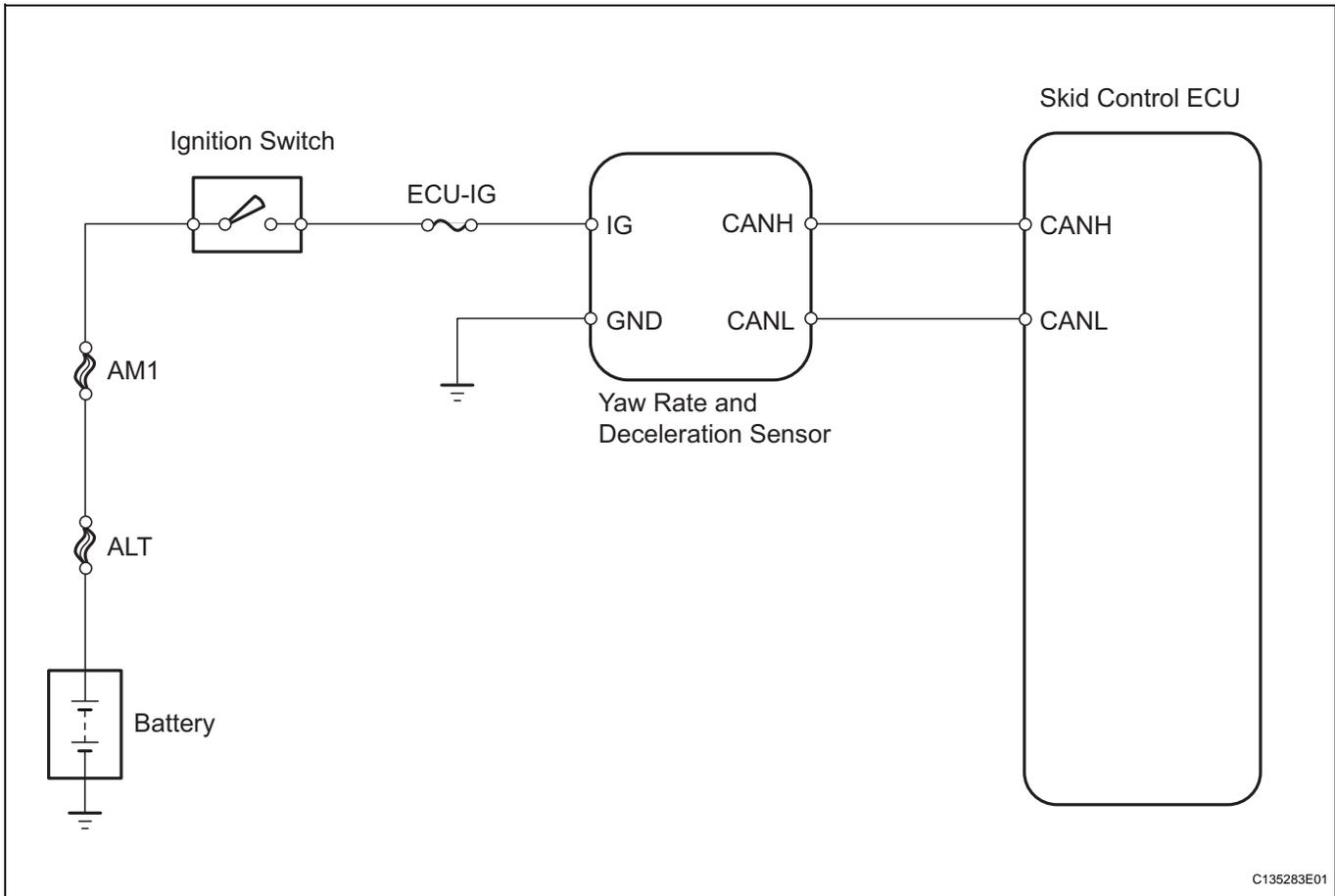
If there is trouble in the bus lines between the yaw rate sensor and deceleration sensor and the CAN communication system, DTC U0123/62 (yaw rate sensor communication trouble) and U0124/95 (deceleration sensor communication trouble) are output.

<b>DTC No.</b>	<b>DTC Detecting Conditions</b>	<b>Trouble Areas</b>
C0371/71	Detected only during test mode	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>
C1232/32	At vehicle speed of 6 mph (10 km/h) or more, signal from either GL1 or GL2 does not change for 30 seconds or more.	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>
C1234/34	Sensor malfunction signal received from yaw rater sensor.	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>
C1243/43	Following condition repeats 16 times. <ul style="list-style-type: none"> <li>• GL1 and GL2 do not change by more than 2LSB when vehicle decelerates from 19 mph (30 km/h) to 0 mph (0 km/h).</li> </ul>	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>
C1244/44	When either of following (1 or 2) detected: <ol style="list-style-type: none"> <li>Both of following conditions continue for at least 60 seconds. <ol style="list-style-type: none"> <li>Vehicle stopped.</li> <li>Difference between GL1 and GL2 does not drop below 0.4 G once it reaches 0.6 G or more.</li> </ol> </li> <li>Data malfunction signal received from deceleration sensor.</li> </ol>	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>
C1245/45	Following condition continues for at least 60 seconds. <ul style="list-style-type: none"> <li>• Difference between values calculated from deceleration sensor value and vehicle speed exceeds 0.35 G.</li> </ul>	<ul style="list-style-type: none"> <li>• Yaw rate and deceleration sensor</li> <li>• Yaw rate and deceleration sensor circuit</li> <li>• CAN communication system</li> </ul>

DTC No.	DTC Detecting Conditions	Trouble Areas
C1279/79	Detected only during test mode	<ul style="list-style-type: none"> <li>Yaw rate and deceleration sensor</li> <li>Yaw rate and deceleration sensor circuit</li> </ul>
C1381/97	Deceleration sensor power source malfunction signal received for at least 10 seconds at speed of more than 2 mph (3 km/h).	<ul style="list-style-type: none"> <li>Yaw rate and deceleration sensor</li> <li>Yaw rate and deceleration sensor circuit</li> </ul>

BC

**WIRING DIAGRAM**



**INSPECTION PROCEDURE**

**NOTICE:**

When replacing the yaw rate and deceleration sensor, perform zero point calibration (See page [BC-24](#)).

**HINT:**

When U0073/94, U0123/62, U0124/95 or U0126/63 are output together with C1232/32 or C1234/34, inspect and repair the trouble areas indicated by U0073/94, U0123/62, U0124/95 or U0126/63 first.

<b>1</b>	<b>CHECK DTC</b>
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- (a) Clear the DTC(s) (See page [BC-45](#)).
- (b) Check if the DTCs U0073/94, U0123/62, C1210/36 and/or C1336/39 are detected (See page [BC-45](#)).

**Result**

Result	Proceed to
DTC U0073/94, U0123/62, C1210/36 and/or C1336/39 not output	A

Result	Proceed to
DTC U0073/94 and/or U0123/62 output	B
DTC C1210/36 and/or C1336/39 output	C

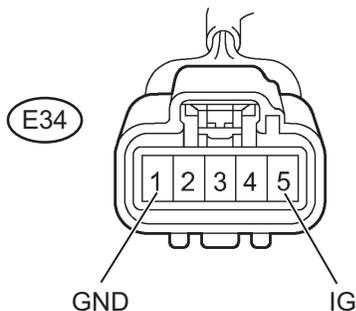
BC

- B** REPAIR CAN COMMUNICATION SYSTEM
- C** REPAIR CIRCUITS INDICATED BY OUTPUT DTCS

**A**

**2 INSPECT YAW RATE AND DECELERATION SENSOR**

Yaw Rate Sensor  
(harness side connector):



- (a) Disconnect the yaw rate and deceleration sensor connector.
- (b) Measure the voltage.  
**Standard voltage**

Tester Connection	Condition	Specified Condition
E34-5 (IG) - Body ground	Ignition switch ON	11 to 14 V

- (c) Measure the resistance.  
**Standard resistance**

Tester Connection	Condition	Specified Condition
E34-1 (GND) - Body ground	Ignition switch OFF	Below 1 Ω

**Result**

Result	Proceed to
OK (When troubleshooting in accordance with DTC CHART)	A
OK (When troubleshooting in accordance with PROBLEM SYMPTOMS TABLE)	B
NG	C

- B** PROCEED TO NEXT CIRCUIT INSPECTION SHOWN IN PROBLEM SYMPTOMS TABLE
- C** REPAIR OR REPLACE HARNESS OR CONNECTOR

**A**

**REPLACE YAW RATE AND DECELERATION SENSOR**